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Wuppertal, 01.06.2013

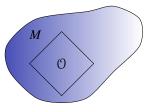
<sup>&</sup>lt;sup>1</sup>Based on the joint work with Klaus Fredenhagen and Romeo Brunetti

#### Outline of the talk

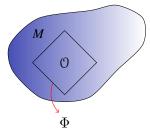
- Introduction
  - Effective quantum gravity
  - Local covariance
- Classical theory
  - Kinematical structure
  - Equations of motion and symmetries
  - BV complex
- Quantization
  - Deformation quantization
  - Background independence

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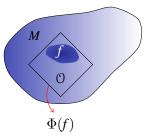
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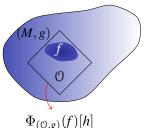
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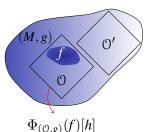
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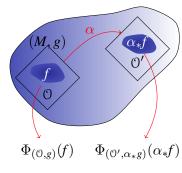


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- Diffeomorphism transformation: move our experimental setup to a different region O'.



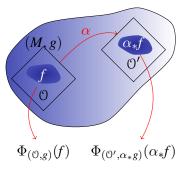
# How to implement it?

• To compare  $\Phi_{(0,g)}(f)$  and  $\Phi_{(0',\alpha_*g)}(\alpha_*f)$  we need to know what does it mean to have "the same observable in a different region".



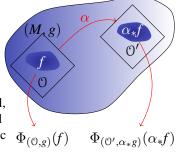


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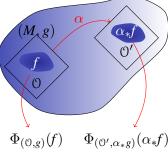
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  - Vec with (small) topological vector spaces as objects and injective continuous homomorphisms of topological vector spaces as morphisms.





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- We define a contravariant functor  $\mathfrak{E}: \mathbf{Loc} \to \mathbf{Vec}$ , which assigns to a spacetime the corresponding configuration space and acts on morphisms  $\chi: \mathcal{M} \to \mathcal{N}$  as  $\mathfrak{E}\chi = \chi^*: \mathfrak{E}(\mathcal{N}) \to \mathfrak{E}(\mathcal{M})$ .



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- We define a contravariant functor €: Loc → Vec, which assigns to a spacetime the corresponding configuration space and acts on morphisms χ : M → N as €χ = χ\* : €(N) → €(M).
- In a similar way we define a covariant functor  $\mathfrak{E}_c : \mathbf{Loc} \to \mathbf{Vec}$  by setting  $\mathfrak{E}\chi = \chi_*$ , where:

$$\chi_* h \doteq \left\{ \begin{array}{ll} (\chi^{-1})^* h(x) &, & x \in \chi(M), \\ 0 &, & \text{else} \end{array} \right.$$

# Functionals and dynamics

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$$\begin{aligned} \operatorname{supp} F &= \{x \in M | \forall \text{ neighbourhoods } U \text{ of } x \ \exists h_1, h_2 \in \mathfrak{E}(\mathfrak{M}), \\ \operatorname{supp} h_2 &\subset U \text{ such that } F(h_1 + h_2) \neq F(h_1) \} \ . \end{aligned}$$

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- F is local if it is of the form:  $F(h) = \int_M f(j_x(h))(x)$ , where f is a density-valued function on the jet bundle over M and  $j_x(h)$  is the jet of  $\varphi$  at the point x.

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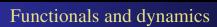
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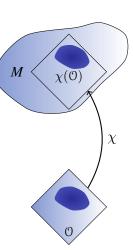
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- $\mathfrak{F}(\mathcal{M}) \doteq$  the space of multilocal functionals (products of local).
- To implement dynamics we use a certain generalization of the Lagrange formalism of classical mechanics.
- For GR the action takes the form:

$$S_{(M,g)}(f)[h] \doteq \int R[\tilde{g}]f \,\mathrm{d}\,\operatorname{vol}_{(M,\tilde{g})}, \quad \tilde{g} = g + h.$$



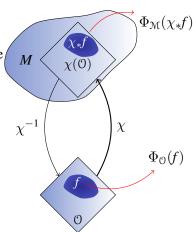
#### Fields as natural transformations

• In the framework of locally covariant field theory [Brunetti-Fredenhagen-Verch 2003], fields are natural transformation between certain functors. Let  $\Phi \in \operatorname{Nat}(\mathfrak{D},\mathfrak{F})$ , where  $\mathfrak{D}$  is the functor of test function spaces  $\mathfrak{D}(\mathcal{M}) = \mathfrak{C}_c^{\infty}(M)$  (one could substitute  $\mathfrak{F}$  with a functor to the category of Poisson or  $C^*$ -algebras).



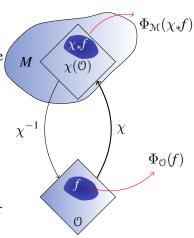
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- $\Phi$  is a natural transformation if  $\Phi_{\mathcal{O}}(f)[\chi^*h] = \Phi_{\mathcal{M}}(\chi_*f)[h]$  holds.
- In classical gravity we understand physical quantities not as pointwise objects but rather as something defined on all the spacetimes in a coherent way.





## Equations of motion and symmetries

• The Euler-Lagrange derivative of *S* is defined by

$$\left\langle S_M'(\tilde{g}), h_1 \right\rangle = \left\langle S_M(f)^{(1)}(\tilde{g}), h_1 \right\rangle$$
, where  $f \equiv 1$  on  $\operatorname{supp} h_1$ .
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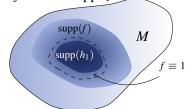


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• Abstractly,  $S'_M$  is a 1-form on  $\mathfrak{E}(M)$ . The field equation is:  $S'_M(\tilde{g}) = 0$ .





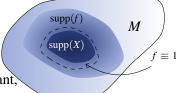
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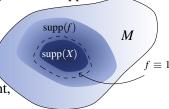
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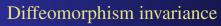
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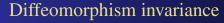


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- Let  $\mathfrak{E}_S(M)$  denote the space of solutions of field equations. We want to characterise the space of functionals on  $\mathfrak{E}_S(M)$  which are invariant under all the local symmetries of S: invariant on-shell functionals  $\mathfrak{F}_S^{\text{inv}}(M)$ . In a finite dimensional case this space has a clear homological interpretation.



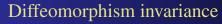


- For GR symmetries are infinitesimal diffeomorphisms, i.e. elements of  $\mathfrak{X}(\mathcal{M}) \doteq \Gamma_c(TM)$ . Let us choose a sequence  $\vec{\xi} = (\xi_{\mathcal{M}})_{\mathcal{M} \in \text{Obj}(\mathbf{Loc})}, \, \xi_{\mathcal{M}} \in \mathfrak{X}(\mathcal{M})$ .
- After applying the exponential map we obtain  $\alpha_{\mathbb{M}} \doteq \exp(\xi_{\mathbb{M}})$ .
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- Diffeomorphism invariance is the statement that  $\vec{\xi}\Phi=0$ .
- Example:  $\int R[\tilde{g}]f \, d \operatorname{vol}_{(M,\tilde{g})}$  is diffeomorphism invariant, but  $\int R[\tilde{g}]f \, d \operatorname{vol}_{(M,g)}$  is not.



# Physical interpretation

• Let us fix  $\mathcal{M}$ . A test tensor  $f \in \mathfrak{Tens}_c(\mathcal{M})$  corresponds to a concrete geometrical setting of an experiment, so for each  $\mathcal{M} \in \mathrm{Obj}(\mathbf{Loc})$ , we obtain a functional  $\Phi(f)$ , which depends covariantly on the geometrical data provided by f.



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- Given  $f \in \mathfrak{Tens}_c(\mathcal{M})$  we recover not only the functional  $\Phi_{\mathcal{M}}(f)$ , but also the whole diffeomorphism class of functionals  $\Phi_{\mathcal{M}}(\alpha_* f)$ , where  $\alpha \in \mathrm{Diff}_c(\mathcal{M})$ .

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#### New insight

Classical (or quantum) fields generate physical quantities, but a concrete observable quantity is obtained by evaluation on a test tensor. New concept: evaluated fields.



#### Evaluation of fields

• In our formalism, the full information about the dependence of a measurement on the geometrical setup should be contained in the family  $(\alpha_* f)_{\alpha \in \text{Diff}_c(\mathcal{M})}$ .



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- Therefore, for a fixed M and  $\Phi$ , a physically meaningful object is the function  $\Phi_f : \mathrm{Diff}_c(M) \ni \alpha \mapsto \Phi_M(\alpha_* f)$ .



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- Therefore, for a fixed  $\mathcal{M}$  and  $\Phi$ , a physically meaningful object is the function  $\Phi_f : \mathrm{Diff}_c(\mathcal{M}) \ni \alpha \mapsto \Phi_{\mathcal{M}}(\alpha_* f)$ .
- Let  $\mathcal{F}$  denote the subspace of  $\mathcal{C}^{\infty}(\mathrm{Diff}_c(\mathcal{M}), \mathfrak{F}(\mathcal{M}))$  generated by elements of the form  $\Phi_f$  with respect to the pointwise product.



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### BV complex

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$$(s\Phi)_{\mathfrak{M}}(f) = \{\Phi_{\mathfrak{M}}(f), S + \gamma\} + \Phi_{\mathfrak{M}}(\pounds_{C}f),$$

where  $C \in \mathfrak{X}(M)$  is the ghost and  $\gamma$  is the Chevalley-Eilenberg differential, which acts on  $\mathcal{BV}$  via infinitesimal diffeomorphism transformations along the ghost fields C. For  $\Phi \in \mathcal{F}$  we have

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• Gauge invariant observables are given by:  $\mathcal{F}_{S}^{inv} := H^{0}(s, \mathcal{BV}).$ 



# Gauge fixing

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- Note that  $H^0(s^{\Psi}, \alpha_{\Psi}(\mathcal{BV})) = H^0(s, \mathcal{BV}) = \mathcal{F}_{\mathcal{S}}^{\text{inv}}$ .



# Equations of motion and Poisson bracket

• As an output of classical field theory we have a graded manifold  $\overline{\mathfrak{E}}(\mathfrak{M})$  and an extended action  $\tilde{S}$ . Now we apply to this data the deformation quantization.



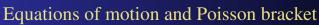
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- For each globally hyperbolic background g, we have the retarded and advanced Green's functions  $\Delta_g^{R/A}$  for the EOM's derived from  $S_0^g$ .
- Using this input, we define the free Poisson bracket on  $\mathcal{BV}$

$$\{F,G\}_0^g \doteq \left\langle F^{(1)}, \Delta_g G^{(1)} \right
angle \qquad \Delta_g = \Delta_g^R - \Delta_g^A \,,$$





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- The deformation quantization of  $(\mathcal{BV}_{\mu c}, \{.,.\}_0^g)$  can be performed in the standard way, by introducing a  $\star$ -product:

$$(F \star_H G) \doteq m \circ \exp(\hbar \Gamma_{\omega_H})(F \otimes G) ,$$

where 
$$\Gamma_{\omega_H} \doteq \int dx \, dy \omega_H(x,y) \frac{\delta}{\delta \varphi(x)} \otimes \frac{\delta}{\delta \varphi(y)}$$
 and

 $\omega_H = \frac{i}{2}\Delta_g + H$  is the Hadamard 2-point function (satisfies the linearized EOM's in both arguments and the  $\mu$ SC).

• For a fixed  $\mathcal{M}$  we have a family of algebras  $\mathfrak{A}_H(\mathcal{M})=(\mathcal{BV}_{\mu c}[[\hbar,\lambda]],\star_H)$ , numbered by possible choices of H. We can define  $\mathfrak{A}(\mathcal{M})$  to be an algebra consisting of families  $(F_H)$ , such that  $F_H=e^{\frac{\hbar}{2}\Gamma'_{H-H'}}F_{H'}$ , where  $\Gamma'_{H-H'}\doteq\int dx\,dy(H-H')(x,y)\frac{\delta^2}{\delta\varphi(x)\delta\varphi(y)}$  and the star product is given by

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• This leads to a deformation quantization  $(\mathfrak{A}(\mathcal{M}),\star)$  of the space of fields.

#### Interaction

• In the next step we have to introduce the interaction, i.e. consider the algebras  $\mathfrak{A}_H(\mathfrak{M})=(\mathfrak{BV}_{\mu c}[[\hbar,\lambda]],\star_H)$  and define on them the renormalized time-ordered products  $\cdot_{\mathfrak{T}_H}$  by the Epstein-Glaser method.

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- Interacting fields are obtained from free ones by the Bogoliubov formula:

$$(R_V(\Phi))_{\mathfrak{M}}(f) \doteq \frac{d}{dt}\Big|_{t=0} S(V^g)^{\star-1} \star S(V^g + t\Phi_{\mathfrak{M}}(f)).$$

### Quantum observables

• In the framework of [K. Fredenhagen, K.R., CMP 2013], the gauge invariance of the *S*-matrix is guaranteed by the so called quantum master equation (QME):

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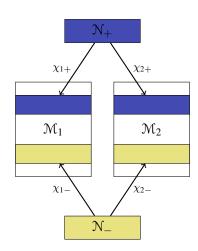
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• If the QME holds, then gauge invariant quantum observables are recovered as the 0th cohomology of the quantum BV operator  $\hat{s} \doteq R_V^{-1} \circ \{., S_0\} \circ R_V$ . Equivalently,

$$\hat{s}\Phi_{\mathcal{M}}(f) = \{., S_0^g + V^g\} + \Phi_{\mathcal{M}}(\pounds_C f) - i\hbar \triangle_{V^g} (\Phi_{\mathcal{M}}(f)).$$

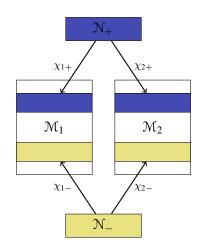
### Relative Cauchy evolution

• Let  $\mathcal{N}_+$  and  $\mathcal{N}_-$  be two spacetimes that embed into two other spacetimes  $\mathcal{M}_1$  and  $\mathcal{M}_2$  around Cauchy surfaces, via causal embeddings given by  $\chi_{k,\pm}, k=1,2$ .



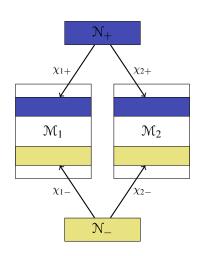
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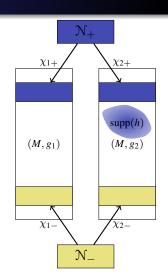


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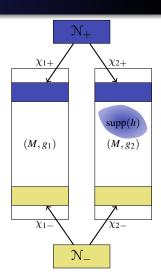
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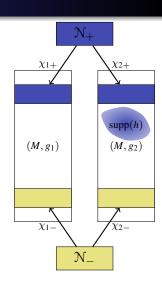
• Let  $\mathcal{M}_1 = (M, g_1)$  and  $\mathcal{M}_2 = (M, g_2)$ , where  $(g_1)_{\mu\nu}$  and  $(g_2)_{\mu\nu}$  differ by a (compactly supported) symmetric tensor  $h_{\mu\nu}$  with  $\sup_{\mu\nu} (h) \cap J^+(\mathcal{N}_+) \cap J^-(\mathcal{N}_-) = \emptyset$ ,



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- The infinitesimal version of the background independence is a condition that  $\Theta_{\mu\nu}=0$ .



#### Theorem [Brunetti, Fredenhagen, K.R. 2013]

The functional derivative  $\Theta_{\mu\nu}$  of the relative Cauchy evolution can be expressed, on-shell, as

$$\Theta_{\mu\nu}(\Phi_{\mathcal{M}_1}(f)) \stackrel{o.s.}{=} [R_{V_1}(\Phi_{\mathcal{M}_1}(f)), R_{V_1}(T_{\mu\nu})]_{\star},$$

where  $T_{\mu\nu}$  is the stress-energy tensor of the extended action and one can define the time-ordered products in such a way that  $T_{\mu\nu}=0$  holds, so the interacting theory is background independent.

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- We have shown, using the relative Cauchy evolution, that our theory is background independent, i.e. independent of the split into free and interacting part.





Thank you for your attention!