# Algebraic Properties of Riccati equations 

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## Summary

- Algebraic properties of Riccati equations?
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- Motivation: Platoon-type spatially invariant systems.
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- False claim by Chris Byrnes, CDC 1980.
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- Applications to spatially invariant systems.
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- The noncommutative case.
- Conclusions.


## Matrix Riccati equation result

Let $A \in \mathbb{C}^{n \times n}, B \in \mathbb{C}^{m \times n}, C \in \mathbb{C}^{n \times p}$. If $(A, B)$ is stabilizable and $(A, C)$ is detectable, then $\exists$ a unique stabilizing solution $P \in \mathbb{C}^{n \times n}$ of

$$
A^{*} P+P A-P B B^{*} P+C^{*} C=0
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Stabilizing solution: $P=P^{*} \geq 0$ and $A-B B^{*} P$ is stable.

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## Fundamental question

Let $\mathfrak{A}$ be a complex Banach algebra, with an involution ${ }^{\dagger}$. When will the following LQR Riccati equation have a unique exponentially stabilizing solution $P \in \mathfrak{A}^{n \times n}$ ?

$$
A^{\dagger} P+P A-P B B^{\dagger} P+C^{\dagger} C=0
$$

Stabilizing solution: $P=P^{\dagger}$ and $A-B B^{\dagger} P$ is exponentially stable, i.e., the semigroup $e^{A t}$ on $\mathfrak{A}^{n \times n}$ is exponentially stable $\Longleftrightarrow$

$$
\sup \{\operatorname{Re} \lambda: \lambda \in \sigma(A)\}<0
$$

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## LQR Riccati equation

Suppose that $Z$ is a Hilbert space and $A, B, C \in \mathcal{L}(Z)$. If $(A, B)$ is exponentially stabilizable and $(A, C)$ is exponentially detectable, then there exists a unique nonnegative solution $P \in \mathcal{L}(Z), P=P^{*} \geq 0$ of the LQR control Riccati equation

$$
A^{*} P+P A-P B B^{*} P+C^{*} C=0 .
$$

There also exists a unique nonnegative solution $Q \in \mathcal{L}(Z)$, $Q=Q^{*} \geq 0$ of the LQR filter Riccati equation

$$
A Q+Q A^{*}-Q C^{*} C Q+B B^{*}=0
$$

Moreover, $A-B B^{*} P$ and $A-Q C C^{*}$ generate exponentially stable semigroups.

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A complex Banach space with a multiplication operation:

- $a, b \in \mathfrak{A} \Longrightarrow a b \in \mathfrak{A}$
- $a(b c)=(a b) c$,
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Involution is a map from $\mathfrak{A}$ to itself: $a \rightarrow a^{\dagger}$ with the properties:

- $(a+b)^{\dagger}=a^{\dagger}+b^{\dagger}$,
- $(\alpha b)^{\dagger}=\bar{\alpha} b^{\dagger}$,
- $(a b)^{\dagger}=a^{\dagger} b^{\dagger}$,
- $\left(a^{\dagger}\right)^{\dagger}=a$.

Commutative complex Banach algebra:

$$
a b=b a \text { for all } a, b \in \mathfrak{A} .
$$

## Example (Even-Weighted Wiener algebra $W_{\alpha}(\mathbb{T})$ )

Let $\alpha=\left(\alpha_{n}\right)_{n \in \mathbb{Z}}$ be any sequence of positive real numbers satisfying

$$
\begin{gathered}
\alpha_{n+m} \leq \alpha_{n} \alpha_{m}, \quad \alpha_{-n}=\alpha_{n} \quad \text { (even) } \\
W_{\alpha}(\mathbb{T}):=\left\{f: f(z)=\sum_{n \in \mathbb{Z}} f_{n} z^{n}, z \in \mathbb{T}=\right.\text { unit circle } \\
\text { and } \left.\|f\|_{W_{\alpha}(\mathbb{T})}:=\sum_{n \in \mathbb{Z}} \alpha_{n}\left|f_{n}\right|<\infty\right\},
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with pointwise operations. $W_{\alpha}(\mathbb{T})$ is a unital commutative Banach algebra contained in the commutative Banach algebra $\mathbf{L}_{\infty}(\mathbb{T})$ with possible involutions:

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\begin{aligned}
f^{\dagger}(z) & :=\overline{f(\bar{z})}=\sum_{n \in \mathbb{Z}} \overline{f_{n}} z^{n}, \\
\text { and } f^{\sim}(z) & :=f(\overline{1 / z})^{*}=\sum_{n \in \mathbb{Z}} \overline{f_{n}} z^{-n} .
\end{aligned}
$$

Consider the subalgebra of bounded convolution operators $T: \ell_{2} \rightarrow \ell_{2}$ given by

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(T x)_{l}=\sum_{r \in \mathbb{Z}} T_{r-l} x_{r} .
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## Motivation: Spatially Invariant Systems

Consider the subalgebra of bounded convolution operators $T: \ell_{2} \rightarrow \ell_{2}$ given by

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Spatially invariant systems: $\Sigma(A, B, C)$ with state space $\ell_{2}\left(\mathbb{Z} ; \mathbb{C}^{n}\right)$.
$A, B, C$ are matrices whose entries are convolution operators and $A, B, C \in \mathcal{L}\left(\ell_{2}\left(\mathbb{Z} ; \mathbb{C}^{n}\right)\right)$, a Banach algebra with the involution the adjoint operation.$^{*}$.

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Under the Fourier transform $\mathfrak{F}: \ell_{2}\left(\mathbb{Z} ; \mathbb{C}^{n}\right) \rightarrow \mathbf{L}_{2}\left(\mathbb{T} ; \mathbb{C}^{n}\right)$. So the study of spatially invariant systems $\Sigma(A, B, C)$ is transformed to the study of the isometrically isomorphic systems
$\Sigma\left(\mathfrak{F} A \mathfrak{F}^{-1}, \mathfrak{F} B \mathfrak{F}^{-1}, \mathfrak{F} C \mathfrak{F}^{-1}\right):=\Sigma(\hat{A}, \hat{B}, \hat{C})$ on $\mathbf{L}_{2}\left(\mathbb{T} ; \mathbb{C}^{n}\right)$. Since $\hat{A}, \hat{B}, \hat{C}$ are multiplication operators on $\mathbf{L}_{\infty}\left(\mathbb{T} ; \mathbb{C}^{n}\right)$ they are much easier to handle mathematically.

## Example

Take $\hat{A}=0, \hat{B}(z)=10-z-1 / z, \hat{C}=1$. The LQR Riccati equation on $\mathbf{L}_{2}(\mathbb{T})$ is

$$
\hat{A}(z)^{*} \hat{P}(z)+\hat{P}(z) \hat{A}(z)-\hat{P}(z) \hat{B}(z) \hat{B}(z)^{*} \hat{P}(z)+\hat{C}(z)^{*} \hat{C}(z)=0 .
$$

This can be solved algebraically for each $z \in \mathbb{T}$ to obtain the unique positive solution

$$
\begin{aligned}
\hat{P}(z) & =\frac{1}{10-z-1 / z} \\
& =\frac{1}{4 \sqrt{6}} \sum_{k \in \mathbb{Z}} \delta^{-|k|} z^{k}
\end{aligned}
$$

where $\delta=5+\sqrt{24}$.

## Control of Platoon-type spatially invariant systems

Discrete spatially invariant operators are in
$\mathcal{L}\left(\ell_{2}\left(\mathbb{Z} ; \mathbb{C}^{n}\right)\right) \simeq \mathcal{L}\left(\mathbf{L}_{2}\left(\mathbb{T} ; \mathbb{C}^{n}\right)\right)=\mathbf{L}_{\infty}\left(\mathbb{T} ; \mathbb{C}^{n \times n}\right)$.

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## Existence of Riccati solutions

If $(\hat{A}(z), \hat{B}(z), \hat{C}(z))$ is stabilizable and detectable for all $z \in \mathbb{T}$ the Riccati equation has a unique s.a stabilizing solution.

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$\sum_{r \in \mathbb{T}} \alpha_{r} p_{r}<\infty$ for some $\left(\alpha_{r}\right)$ or $\hat{P}$ must be in a Wiener algebra $W_{\alpha}(\mathbb{T}) \subset \mathbf{L}_{\infty}(\mathbb{T})$.

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Moreover, the larger the weights $\alpha_{r}$, the better the approximation will be; for example, an exponential weight $\alpha_{r}=e^{|r|}$ would be perfect.

## Gelfand Representation Theorem for commutative Banach algebras

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## Banach algebras

Every commutative Banach algebra is isomorphic to an algebra of continuous functions on its maximal ideal space $M(\mathfrak{A})$ (a compact Hausdorff space, equipped with the weak * topology). The Gelfand transform is a map $\check{:} \mathfrak{A} \rightarrow \mathbb{C}$ given by

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\check{a}(\varphi)=\varphi(a), \quad \forall \varphi \in M(\mathfrak{A}), \quad \forall a \in \mathfrak{A} .
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$$

## Example (The commutative Banach algebra $W_{\alpha}(\mathbb{T})$ )

This has the maximal ideal space which is isomorphic to the $\square$ around $\mathbb{T}$ :

$$
\mathbb{A}(\rho)=\{z \in \mathbb{C}: 1 / \rho \leq|z| \leq \rho\}, \quad \rho=\inf _{n>0} \sqrt[n]{\alpha_{n}}=\lim _{n \rightarrow \infty} \sqrt[n]{\alpha_{n}}
$$

For $f(z)=\sum_{k \in \mathbb{Z}} f_{k} z^{k}$ for $z \in \mathbb{T}$ the Gelfand transform is

$$
\check{f}(z)=\sum_{k \in \mathbb{Z}} f_{k} z^{k} \text { for } z \in \mathbb{A}(\rho), \quad \text { the whole annulus. }
$$

## Claim by Chris Byrnes, CDC 1980

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The idea was to note that the Gelfand transforms $(\check{A}(\varphi), \check{B}(\varphi)), \check{C}(\varphi))$ are just complex matrices and so consider the isomorphic finite-dimensional Riccati equation for each $\varphi$

$$
\left.\left.\left.\left.\check{A}(\varphi)^{*} \check{P}(\varphi)+\check{P}(\varphi) \check{A}(\varphi)-\check{P}(\varphi)\right) \check{B}(\varphi) \check{B}(\varphi)^{*} \check{P}(\varphi)\right)+\check{C}(\varphi)\right)^{*} \check{C}(\varphi)\right)=0
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## Theorem

Suppose that $\mathfrak{A}$ be a commutative, unital, complex Banach algebra, with an involution ${ }^{\dagger}$. Denote by $\check{A}$ the Gelfand transform.
Let $A \in \mathfrak{A}^{n \times n}, B \in \mathfrak{A}^{n \times m}, C \in \mathfrak{A}^{p \times n}$ be such that for all $\varphi \in M(\mathfrak{A})$, $(\check{A}(\varphi), \check{B}(\varphi))$ is controllable and $(\check{A}(\varphi), \check{C}(\varphi))$ is observable. Then there exists a solution $P \in \mathfrak{A}^{n \times n}$ such that

$$
\begin{equation*}
A^{\dagger} P+P A-P B B^{\dagger} P+C^{\dagger} C=0 \tag{1}
\end{equation*}
$$

and $A-B B^{\dagger} P$ is asymptotically stable.
FALSE: The involution.$^{\dagger}$ needs to match the complex conjugate.

## New result by Amol Sasane (special case of SIAM 2011 paper)

Let $\mathfrak{A}$ be a commutative, unital, complex, semisimple Banach algebra. Suppose that $A \in \mathfrak{A}^{n \times n}, B \in \mathfrak{A}^{n \times m}, C \in \mathfrak{A}^{p \times n}$ satisfy the following for all $\varphi \in M(\mathfrak{A})$,
(A1) $\left(\check{A^{\dagger}}\right)(\varphi)=(\check{A}(\varphi))^{*},\left(\check{B^{\dagger}}\right)(\varphi)=(\check{B}(\varphi))^{*},\left(\check{C^{\dagger}}\right)(\varphi)=(\check{C}(\varphi))^{*}$.
(A2) $(\check{A}(\varphi), \check{B}(\varphi))$ is stabilizable,
(A3) $(\check{A}(\varphi), \check{C}(\varphi))$ is detectable.
Then there exists a $P \in \mathfrak{A}^{n \times n}$ such that

- $A^{\dagger} P+P A-P B B^{\dagger} P+C^{\dagger} C=0$,
- $A-B B^{\dagger} P$ is exponentially stable, and $P^{\dagger}=P$.


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Note: condition (A1) on the involution: it needs to match complex conjugation: In general $f^{\dagger}(z):=\overline{f(\bar{z}) h} \neq f(z)^{*}, \quad f^{\sim}(z):=f(\overline{1 / z})^{*} \neq f(z)^{*}$.

Banach algebras satisfying (A1) = symmetric Banach algebras.

## Example (Symmetric even-weighted Wiener algebras)

Gelfand-Raikov-Shilov condition on the weights $\alpha_{n}$ :

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When the Gelfand-Raikov-Shilov condition is satisfied, the annulus $\mathbb{A}(\rho)$ degenerates to the circle $\mathbb{T}$, and for the Banach algebra $W_{\alpha}(\mathbb{T})$ the involution $\cdot \sim$ reduces to

$$
f^{\sim}(z):=f(z)^{*} \quad(z \in \mathbb{T}), \text { for } f \in W_{\alpha}(\mathbb{T})
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With this involution $W_{\alpha}(\mathbb{T})$ is a symmetric Banach algebra.
Thus for matrices $A, B, C$ with entries from $W_{\alpha}(\mathbb{T})$ their involution is the usual Hermitian adjoint operation: $A^{\sim}(z)=A(z)^{*}$ and assumption (A1) is always satisfied.

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## LQR control of spatially invariant systems

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## Claim by Motee and Jadbabaie, IEEE 2008

They considered LQR control of a general class of spatially distributed systems. These include the platoon type spatially invariant systems whose operators have components in the even-weighted algebras $W_{\alpha}(\mathbb{T})$. In particular, $W_{\tau}(\mathbb{T})$ with the exponential weights $\alpha_{n}=e^{\tau|n|}$.

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Theorem: spatially invariant scalar case
If $A, B, C \in W_{\tau}(\mathbb{T})$ and the LQR Riccati equation

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has a unique positive definite solution $P \in \mathcal{L}\left(\mathbf{L}_{2}(\mathbb{T})\right)$, then $P \in W_{\tau}(\mathbb{T})$.

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Counterexample: Ruth Curtain, IEEE 2008.

## The noncommutative case

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- $\|A\|_{\mathfrak{A}} \geq M\|A\|_{\mathcal{L}(Z)}$.

If $A, B, C \in \mathfrak{A}$ and $(A, B, C)$ is exponentially stabilizable and detectable wrt $Z$, then $P \in \mathfrak{A}$, where $P \in \mathcal{L}(Z)$ is the unique nonnegative solution to the control Riccati equations:

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With recent results by Gröchenig \& Leinert (2006) this result covers the spatially distributed LQR problem posed by Motee \& Jadbabaie.

## Curious

An essential step in the proof uses the following result from Curtain \& Opmeer MCSS, 2006:
Let $P, Q$ be the self-adjoint solutions to the control and filter Riccati equations

$$
\begin{aligned}
A^{*} P+P A-P B B^{*} P+C^{*} C & =0 \\
Q A+Q A^{*}-Q C^{*} C Q+B^{*} B & =0
\end{aligned}
$$

Then the solution to the following Lyapunov equation

$$
\left(A-B B^{*} P\right) X+X\left(A-B B^{*} P\right)^{*}=-B B^{*}
$$

is $X=P(I+P Q)^{-1}$.

## Conclusions

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- Recent results: algebraic properties of the LQR Riccati equation for inverse-closed noncommutative algebras.
- The results have direct applications to spatially distributed systems.
- Generalization to the algebraic properties of the LQR Riccati equation when $A$ is an unbounded operator on $\mathfrak{A}$ but it generates a semigroup on $\mathfrak{A}$.


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