Byrnes-Isidori form for infinite dimensional systems

Carsten Trunk

joint work with A. Ilchmann (Ilmenau) and B. Jacob (Wuppertal)

TU Ilmenau

19. July 2011



$$\dot{z}(t) = Az(t) + u(t)b, \quad z(0) = z_0,$$

 $y(t) = (z(t), c).$

$$\dot{z}(t) = Az(t) + u(t)b, \quad z(0) = z_0,$$

 $y(t) = (z(t), c).$

 \bullet $(H,(\cdot,\cdot))$ Hilbert space,

$$\dot{z}(t) = Az(t) + u(t)b, \quad z(0) = z_0,$$

 $y(t) = (z(t), c).$

- \bullet $(H,(\cdot,\cdot))$ Hilbert space,
- ② $A : dom A \rightarrow H$ generator of a C_0 -semigroup,

$$\dot{z}(t) = Az(t) + u(t)b, \quad z(0) = z_0,$$

 $y(t) = (z(t), c).$

- \bullet $(H,(\cdot,\cdot))$ Hilbert space,
- ② $A : dom A \rightarrow H$ generator of a C_0 -semigroup,
- $u \in L^1_{loc}(\mathbb{R}^+,\mathbb{R}),$

$$\dot{z}(t) = Az(t) + u(t)b, \quad z(0) = z_0,$$

 $y(t) = (z(t), c).$

- \bullet $(H,(\cdot,\cdot))$ Hilbert space,
- ② $A : dom A \rightarrow H$ generator of a C_0 -semigroup,
- $u \in L^1_{loc}(\mathbb{R}^+,\mathbb{R}),$
- Relative degree r:

$$\dot{z}(t) = Az(t) + u(t)b, \quad z(0) = z_0,$$

 $y(t) = (z(t), c).$

- $(H, (\cdot, \cdot))$ Hilbert space,
- ② $A : \text{dom } A \rightarrow H \text{ generator of a } C_0\text{-semigroup,}$
- $u \in L^1_{loc}(\mathbb{R}^+,\mathbb{R}),$
- Relative degree r:

$$b \in \text{dom } A^r$$
 and $c \in \text{dom } A^{*^r}$

and

$$(A^{r-1}b, c) \neq 0$$
 and for $j = 0, 1, ..., r-2$ we have $(A^{j}b, c) = 0$.

Lemma

Assume we have relative degree r. Then

$$H = Is\{c\} + Is\{A^*c\} + \cdots + Is\{A^{*^{r-1}}c\} + H_0,$$
 (1)

where

$$H_0 := \{b\}^{\perp} \cap \{Ab\}^{\perp} \cap \dots \cap \{A^{r-1}b\}^{\perp}.$$
 (2)

Theorem

With respect to $H = ls\{c\} + ls\{A^*c\} + \cdots + ls\{A^{*^{r-1}}c\} + H_0$:

$$x = (P^{0}x)c + (P^{1}x)A^{*}c + \dots + (P^{r-1}x)A^{*r-1}c + P_{H_{0}}x,$$

where $P^0x, \ldots, P^{r-1}: H \to \mathbb{R}$ (except for P_{H_0}):

Theorem

With respect to $H = ls\{c\} + ls\{A^*c\} + \cdots + ls\{A^{*r-1}c\} + H_0$:

$$x = (P^{0}x)c + (P^{1}x)A^{*}c + \dots + (P^{r-1}x)A^{*r-1}c + P_{H_{0}}x,$$

where $P^0x,\ldots,P^{r-1}:H o\mathbb{R}$ (except for P_{H_0}): $j=m+2,\ldots,r$

$$P_{j}^{m}x := \left(\frac{\left(A^{*^{j-1}}c, A^{r-(m+1)}b\right)}{(c, A^{r-1}b)} - \sum_{k=m+2}^{j-1} P_{k}^{m}A^{*^{j-1}}c\right) \frac{(x, A^{r-j}b)}{(c, A^{r-1}b)},$$

$$P^m x := \frac{(x, A^{r-(m+1)}b)}{(c, A^{r-1}b)} - \sum_{j=m+2}^r P_j^m x, \quad m = 0, \dots, r-1,$$

Theorem

With respect to $H = ls\{c\} + ls\{A^*c\} + \cdots + ls\{A^{*r-1}c\} + H_0$:

$$x = (P^{0}x)c + (P^{1}x)A^{*}c + \dots + (P^{r-1}x)A^{*r-1}c + P_{H_{0}}x,$$

where $P^0x,\ldots,P^{r-1}:H\to\mathbb{R}$ (except for P_{H_0}): $j=m+2,\ldots,r$

$$P_{j}^{m}x := \left(\frac{\left(A^{*^{j-1}}c, A^{r-(m+1)}b\right)}{(c, A^{r-1}b)} - \sum_{k=m+2}^{j-1} P_{k}^{m}A^{*^{j-1}}c\right) \frac{(x, A^{r-j}b)}{(c, A^{r-1}b)},$$

$$P^{m}x := \frac{(x, A^{r-(m+1)}b)}{(c, A^{r-1}b)} - \sum_{j=m+2}^{r} P_{j}^{m}x, \quad m = 0, \dots, r-1,$$

$$P_{H_0}x := x - \sum_{j=0}^{r-1} (P^j x) A^{*^j} c.$$

$$\widehat{A} = \begin{bmatrix} 0 & 1 & \cdots & 0 & 0 \\ 0 & 0 & \ddots & 0 & 0 \\ \vdots & \vdots & & 1 & 0 \\ P^{0}A^{*'}c & P^{1}A^{*'}c & \cdots & P^{r-1}A^{*'}c & S \\ R & 0 & \cdots & 0 & Q \end{bmatrix}$$

$$\widehat{A} = \begin{bmatrix} 0 & 1 & \cdots & 0 & 0 \\ 0 & 0 & \ddots & 0 & 0 \\ \vdots & \vdots & & 1 & 0 \\ P^{0}A^{*'}c & P^{1}A^{*'}c & \cdots & P^{r-1}A^{*'}c & S \\ R & 0 & \cdots & 0 & Q \end{bmatrix}$$

$$R\alpha = \frac{\alpha}{(c, A^{r-1}b)} P^{\perp} A^r b$$
, where P^{\perp} : orthogonal Proj. on H_0 ,

$$\widehat{A} = \begin{bmatrix} 0 & 1 & \cdots & 0 & 0 \\ 0 & 0 & \ddots & 0 & 0 \\ \vdots & \vdots & & 1 & 0 \\ P^0 A^{*'} c & P^1 A^{*'} c & \cdots & P^{r-1} A^{*'} c & S \\ R & 0 & \cdots & 0 & Q \end{bmatrix}$$

$$Rlpha=rac{lpha}{(c,A^{r-1}b)}P^{\perp}A^{r}b, \quad ext{where } P^{\perp}: ext{ orthogonal Proj. on } H_{0},$$
 $S\eta=\left(P_{H_{0}}A^{*^{r}}c,\eta
ight)$

$$\widehat{A} = \begin{bmatrix} 0 & 1 & \cdots & 0 & 0 \\ 0 & 0 & \ddots & 0 & 0 \\ \vdots & \vdots & & 1 & 0 \\ P^0 A^{*'} c & P^1 A^{*'} c & \cdots & P^{r-1} A^{*'} c & S \\ R & 0 & \cdots & 0 & Q \end{bmatrix}$$

$$Rlpha=rac{lpha}{(c,A^{r-1}b)}P^\perp A^r b, \quad ext{where } P^\perp: ext{ orthogonal Proj. on } H_0,$$
 $S\eta=\left(P_{H_0}A^{*^r}c,\eta
ight)$ $Q\eta=P^\perp A\eta \quad ext{for } \eta\in H_0\cap ext{dom } A.$

Set dom $\widehat{A} := \mathbb{R}^r \times (H_0 \cap \text{dom } A)$ and define \widehat{A} in $\mathbb{R}^r \times H_0$

$$\widehat{A} = \begin{bmatrix} 0 & 1 & \cdots & 0 & 0 \\ 0 & 0 & \ddots & 0 & 0 \\ \vdots & \vdots & & 1 & 0 \\ P^{0}A^{*'}c & P^{1}A^{*'}c & \cdots & P^{r-1}A^{*'}c & S \\ R & 0 & \cdots & 0 & Q \end{bmatrix}$$

Theorem

$$U: H \to \mathbb{R}^r \times H_0, \qquad x \mapsto Ux := \begin{pmatrix} P^0x \\ \vdots \\ P^{r-1}x \\ P_{H_0}x \end{pmatrix}.$$

Then we have

$$AU^* = U^*\widehat{A}.$$

$$\dot{z}(t) = Az(t) + u(t)b, \quad y(t) = (z(t), c).$$

$$\dot{z}(t) = Az(t) + u(t)b, \quad y(t) = (z(t), c).$$

Set

$$x := (U^{-1})^* z$$
 use:

$$\dot{z}(t) = Az(t) + u(t)b, \quad y(t) = (z(t), c).$$

Set

$$x := (U^{-1})^* z$$
 use: $AU^* = U^* \widehat{A} \Leftrightarrow$

$$\dot{z}(t) = Az(t) + u(t)b, \quad y(t) = (z(t), c).$$

Set

$$x := (U^{-1})^* z$$
 use: $AU^* = U^* \widehat{A} \Leftrightarrow (U^{-1})^* A = \widehat{A}(U^{-1})^*$.

$$\dot{z}(t) = Az(t) + u(t)b, \quad y(t) = (z(t), c).$$

Set

$$x := (U^{-1})^* z$$
 use: $AU^* = U^* \widehat{A} \Leftrightarrow (U^{-1})^* A = \widehat{A}(U^{-1})^*$.

$$\dot{x} = (U^{-1})^* \dot{z} =$$

$$\dot{z}(t) = Az(t) + u(t)b, \quad y(t) = (z(t), c).$$

Set

$$x := (U^{-1})^* z$$
 use: $AU^* = U^* \widehat{A} \Leftrightarrow (U^{-1})^* A = \widehat{A}(U^{-1})^*$.

$$\dot{x} = (U^{-1})^* \dot{z} = (U^{-1})^* Az + (U^{-1})^* bu =$$

$$\dot{z}(t) = Az(t) + u(t)b, \quad y(t) = (z(t), c).$$

Set

$$x := (U^{-1})^* z$$
 use: $AU^* = U^* \widehat{A} \Leftrightarrow (U^{-1})^* A = \widehat{A}(U^{-1})^*$.

$$\dot{x} = (U^{-1})^* \dot{z} = (U^{-1})^* Az + (U^{-1})^* bu = \widehat{A}x + \begin{pmatrix} 0 \\ \vdots \\ 0 \\ (A^{r-1}b,c) \\ 0 \end{pmatrix} u,$$

$$\dot{z}(t) = Az(t) + u(t)b, \quad y(t) = (z(t), c).$$

Set

$$x := (U^{-1})^* z$$
 use: $AU^* = U^* \widehat{A} \Leftrightarrow (U^{-1})^* A = \widehat{A}(U^{-1})^*$.

$$\dot{x} = (U^{-1})^* \dot{z} = (U^{-1})^* Az + (U^{-1})^* bu = \widehat{A}x + \begin{pmatrix} \vdots \\ 0 \\ (A^{r-1}b,c) \\ 0 \end{pmatrix} u,$$

$$y = (z, c)$$

$$\dot{z}(t) = Az(t) + u(t)b, \quad y(t) = (z(t), c).$$

Set

$$x := (U^{-1})^* z$$
 use: $AU^* = U^* \widehat{A} \Leftrightarrow (U^{-1})^* A = \widehat{A}(U^{-1})^*$.

$$\dot{x} = (U^{-1})^* \dot{z} = (U^{-1})^* Az + (U^{-1})^* bu = \widehat{A}x + \begin{pmatrix} 0 \\ \vdots \\ 0 \\ (A^{r-1}b,c) \\ 0 \end{pmatrix} u,$$

$$y = (z, c) = (U^*x, c) =$$

$$\dot{z}(t) = Az(t) + u(t)b, \quad y(t) = (z(t), c).$$

Set

$$x := (U^{-1})^* z$$
 use: $AU^* = U^* \widehat{A} \Leftrightarrow (U^{-1})^* A = \widehat{A}(U^{-1})^*$.

$$\dot{x} = (U^{-1})^* \dot{z} = (U^{-1})^* Az + (U^{-1})^* bu = \widehat{A}x + \begin{pmatrix} 0 \\ \vdots \\ 0 \\ (A^{r-1}b,c) \\ 0 \end{pmatrix} u,$$

$$y = (z, c) = (U^*x, c) = (x, Uc) =$$

$$\dot{z}(t) = Az(t) + u(t)b, \quad y(t) = (z(t), c).$$

Set

$$x := (U^{-1})^* z$$
 use: $AU^* = U^* \widehat{A} \Leftrightarrow (U^{-1})^* A = \widehat{A}(U^{-1})^*$.

$$\dot{x} = (U^{-1})^* \dot{z} = (U^{-1})^* Az + (U^{-1})^* bu = \widehat{A}x + \begin{pmatrix} 0 \\ \vdots \\ 0 \\ (A^{r-1}b,c) \\ 0 \end{pmatrix} u,$$

$$y = (z,c) = (U^*x,c) = (x,Uc) = \begin{pmatrix} x, \begin{pmatrix} 1\\0\\ \vdots\\0 \end{pmatrix} \end{pmatrix}_{\mathbb{R}^r \times H_0}.$$

Rewrite the system in Byrnes-Isidori form

Theorem

$$\dot{z} = Az + ub, \quad y = (z, c).$$

Rewrite the system in Byrnes-Isidori form

Theorem

$$\dot{z} = Az + ub, \quad y = (z, c).$$

$$\Leftrightarrow$$

$$\dot{x} = \begin{bmatrix}
0 & 1 & \cdots & 0 & 0 \\
0 & 0 & \ddots & 0 & 0 \\
\vdots & \vdots & & 1 & 0 \\
P^0 A^{*r} c & P^1 A^{*r} c & \cdots & P^{r-1} A^{*r} c & S \\
R & 0 & \cdots & 0 & Q
\end{bmatrix} x + \begin{pmatrix}
0 \\ \vdots \\ 0 \\ (A^{r-1} b, c) \\ 0
\end{pmatrix} u,$$

$$y = \begin{pmatrix}
x, \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}
\end{pmatrix}$$
.

 $(b,c)\neq 0.$

$$(b,c)\neq 0.$$

Lemma

$$H = sp\{c\} \dotplus \{b\}^{\perp}.$$

$$(b,c)\neq 0.$$

Lemma

$$H = sp\{c\} \dotplus \{b\}^{\perp}.$$

$$\begin{pmatrix} \dot{z}_1(t) \\ \dot{z}_2(t) \end{pmatrix} = \begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix} \begin{pmatrix} z_1(t) \\ z_2(t) \end{pmatrix} + \begin{pmatrix} u(t)(b,c) \\ 0 \end{pmatrix}$$

$$(b,c)\neq 0.$$

Lemma

$$H = sp\{c\} \stackrel{\cdot}{+} \{b\}^{\perp}.$$

$$\begin{pmatrix} \dot{z}_1(t) \\ \dot{z}_2(t) \end{pmatrix} = \begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix} \begin{pmatrix} z_1(t) \\ z_2(t) \end{pmatrix} + \begin{pmatrix} u(t)(b,c) \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} z_1(0) \\ z_2(0) \end{pmatrix} = \begin{pmatrix} z_1^0 \\ z_2^0 \end{pmatrix}$$

$$(b,c)\neq 0.$$

Lemma

$$H = sp\{c\} \stackrel{\cdot}{+} \{b\}^{\perp}.$$

$$\begin{pmatrix} \dot{z}_1(t) \\ \dot{z}_2(t) \end{pmatrix} = \begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix} \begin{pmatrix} z_1(t) \\ z_2(t) \end{pmatrix} + \begin{pmatrix} u(t)(b,c) \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} z_1(0) \\ z_2(0) \end{pmatrix} = \begin{pmatrix} z_1^0 \\ z_2^0 \end{pmatrix}$$

$$y(t) = z_1(t)$$

Funnel

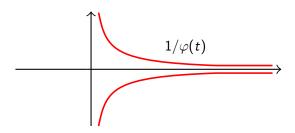
Let
$$\varphi$$
 smooth, $\varphi(0)=0$, $\varphi(t)>0$, $\liminf_{t\to\infty}\varphi(t)>0$.

$$\mathcal{F}_{arphi} := \mathrm{graph} \ \Big(t \mapsto ig\{ z \in \mathbb{R} ig| \ \ arphi(t) |z| < 1 ig\} \Big).$$

Funnel

Let φ smooth, $\varphi(0) = 0$, $\varphi(t) > 0$, $\liminf_{t \to \infty} \varphi(t) > 0$.

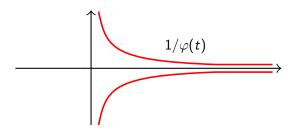
$$\mathcal{F}_{arphi} := \mathrm{graph} \ \Big(t \mapsto ig\{ z \in \mathbb{R} ig| \ \ arphi(t) |z| < 1 ig\} \Big).$$



Funnel

Let φ smooth, $\varphi(0) = 0$, $\varphi(t) > 0$, $\liminf_{t \to \infty} \varphi(t) > 0$.

$$\mathcal{F}_{arphi} := ext{graph } \Big(t \mapsto ig\{ z \in \mathbb{R} ig| \;\; arphi(t) |z| < 1 ig\} \Big).$$



For a cont. differentiable bounded reference y_{ref} let

$$u(t) = -k(t)\operatorname{sgn}(b,c)e(t), \ k(t) = \frac{1}{1-\varphi(t)|e(t)|}, \ e(t) = y(t) - y_{\operatorname{ref}}(t).$$

$$u(t) = -k(t)\operatorname{sgn}(b,c)e(t), \ k(t) = \frac{1}{1-\varphi(t)|e(t)|}, \ e(t) = y(t) - y_{\operatorname{ref}}(t).$$

$$u(t) = -k(t)\operatorname{sgn}(b,c)e(t), \ k(t) = \frac{1}{1-\varphi(t)|e(t)|}, \ e(t) = y(t) - y_{\operatorname{ref}}(t).$$

$$\begin{pmatrix} \dot{z}_1(t) \\ \dot{z}_2(t) \end{pmatrix} = \begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix} \begin{pmatrix} z_1(t) \\ z_2(t) \end{pmatrix} + \begin{pmatrix} u(t)(b,c) \\ 0 \end{pmatrix}, \quad \begin{pmatrix} z_1(0) \\ z_2(0) \end{pmatrix} = \begin{pmatrix} z_1^0 \\ z_2^0 \end{pmatrix}$$

$$u(t) = -k(t)\operatorname{sgn}(b,c)e(t), \ k(t) = \frac{1}{1-\varphi(t)|e(t)|}, \ e(t) = y(t) - y_{\operatorname{ref}}(t).$$

$$\begin{pmatrix} \dot{z}_1(t) \\ \dot{z}_2(t) \end{pmatrix} = \begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix} \begin{pmatrix} z_1(t) \\ z_2(t) \end{pmatrix} + \begin{pmatrix} u(t)(b,c) \\ 0 \end{pmatrix}, \quad \begin{pmatrix} z_1(0) \\ z_2(0) \end{pmatrix} = \begin{pmatrix} z_1^0 \\ z_2^0 \end{pmatrix}$$

$$y(t) = z_1(t)$$

$$u(t) = -k(t)\operatorname{sgn}(b,c)e(t), \ k(t) = \frac{1}{1-\varphi(t)|e(t)|}, \ e(t) = y(t) - y_{\operatorname{ref}}(t).$$

$$\begin{pmatrix} \dot{z}_1(t) \\ \dot{z}_2(t) \end{pmatrix} = \begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix} \begin{pmatrix} z_1(t) \\ z_2(t) \end{pmatrix} + \begin{pmatrix} u(t)(b,c) \\ 0 \end{pmatrix}, \quad \begin{pmatrix} z_1(0) \\ z_2(0) \end{pmatrix} = \begin{pmatrix} z_1^0 \\ z_2^0 \end{pmatrix}$$

$$y(t) = z_1(t)$$

Theorem

Assume A_4 is the generator of an exponentially stable semigroup

$$u(t) = -k(t)\operatorname{sgn}(b,c)e(t), \ k(t) = \frac{1}{1-\varphi(t)|e(t)|}, \ e(t) = y(t) - y_{\operatorname{ref}}(t).$$

$$\begin{pmatrix} \dot{z}_1(t) \\ \dot{z}_2(t) \end{pmatrix} = \begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix} \begin{pmatrix} z_1(t) \\ z_2(t) \end{pmatrix} + \begin{pmatrix} u(t)(b,c) \\ 0 \end{pmatrix}, \quad \begin{pmatrix} z_1(0) \\ z_2(0) \end{pmatrix} = \begin{pmatrix} z_1^0 \\ z_2^0 \end{pmatrix}$$

$$y(t) = z_1(t)$$

Theorem

Assume A_4 is the generator of an exponentially stable semigroup and $y_{\text{ref}} \in W^{1,\infty}(\mathbb{R}^+)$.

$$u(t) = -k(t)\operatorname{sgn}(b,c)e(t), \ k(t) = \frac{1}{1-\varphi(t)|e(t)|}, \ e(t) = y(t) - y_{\operatorname{ref}}(t).$$

$$\begin{pmatrix} \dot{z}_1(t) \\ \dot{z}_2(t) \end{pmatrix} = \begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix} \begin{pmatrix} z_1(t) \\ z_2(t) \end{pmatrix} + \begin{pmatrix} u(t)(b,c) \\ 0 \end{pmatrix}, \quad \begin{pmatrix} z_1(0) \\ z_2(0) \end{pmatrix} = \begin{pmatrix} z_1^0 \\ z_2^0 \end{pmatrix}$$

$$y(t) = z_1(t)$$

Theorem

Assume A_4 is the generator of an exponentially stable semigroup and $y_{\rm ref} \in W^{1,\infty}(\mathbb{R}^+)$. The above system with Funnel control has a global solution.

$$u(t) = -k(t)\operatorname{sgn}(b,c)e(t), \ k(t) = \frac{1}{1-\varphi(t)|e(t)|}, \ e(t) = y(t) - y_{\operatorname{ref}}(t).$$

$$\begin{pmatrix} \dot{z}_1(t) \\ \dot{z}_2(t) \end{pmatrix} = \begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix} \begin{pmatrix} z_1(t) \\ z_2(t) \end{pmatrix} + \begin{pmatrix} u(t)(b,c) \\ 0 \end{pmatrix}, \quad \begin{pmatrix} z_1(0) \\ z_2(0) \end{pmatrix} = \begin{pmatrix} z_1^0 \\ z_2^0 \end{pmatrix}$$

$$y(t) = z_1(t)$$

Theorem

Assume A_4 is the generator of an exponentially stable semigroup and $y_{\text{ref}} \in W^{1,\infty}(\mathbb{R}^+)$. The above system with Funnel control has a global solution. Each global solution z and u, k are bounded.

$$u(t) = -k(t)\operatorname{sgn}(b,c)e(t), \ k(t) = \frac{1}{1-\varphi(t)|e(t)|}, \ e(t) = y(t) - y_{\operatorname{ref}}(t).$$

$$\begin{pmatrix} \dot{z}_1(t) \\ \dot{z}_2(t) \end{pmatrix} = \begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix} \begin{pmatrix} z_1(t) \\ z_2(t) \end{pmatrix} + \begin{pmatrix} u(t)(b,c) \\ 0 \end{pmatrix}, \quad \begin{pmatrix} z_1(0) \\ z_2(0) \end{pmatrix} = \begin{pmatrix} z_1^0 \\ z_2^0 \end{pmatrix}$$

$$y(t) = z_1(t)$$

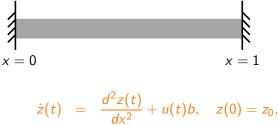
Theorem

Assume A_4 is the generator of an exponentially stable semigroup and $y_{\rm ref} \in W^{1,\infty}(\mathbb{R}^+)$. The above system with Funnel control has a global solution. Each global solution z and u, k are bounded. For all t>0 we have

$$e(t) \in \mathcal{F}_{\varphi}$$
.



Example: Heat equation



$$\dot{z}(t) = \frac{dz(t)}{dx^2} + u(t)b, \quad z(0) = z_0$$

$$\frac{dz(t)}{dx}(0) = \frac{dz(t)}{dx}(0) = 0,$$

$$y(t) = (z(t), c)_{L^2(0,1)}.$$

 $c(x) \equiv 1$, b smooth with compact support in (0,1). $(b,c) \neq 0$, i.e. relative degree 1.

Thank you.