

A NEW \mathcal{V} -METRIC IN CONTROL THEORY

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Outline

(1) What is the metric on?

$$d_v : X \times X \rightarrow [0, \infty)$$

$X =$ set of "unstable control systems"

(2) Why is it needed?

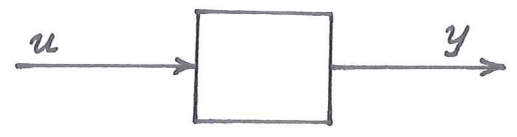
Robust stabilization problem

(3) The "classical" v -metric

G. Vinnicombe ; 1993

(4) Our extension.

Control theory

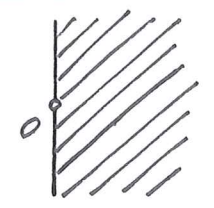


$$\hat{y}(s) = \underset{\substack{\text{transfer} \\ \text{function}}}{g(s)} \hat{u}(s)$$

Stable system: "nice" inputs \mapsto nice outputs

Classes of stable transfer functions

(1) $RH^\infty := H^\infty \cap \mathbb{C}(s)$



$u \in L^2(0, \infty) \Rightarrow y \in L^2(0, \infty)$

(2) $\mathcal{CA}^+ = \left\{ \hat{\mu} : \begin{array}{l} \mu \text{ is a complex Borel measure on } \mathbb{R} \text{ s.t.} \\ \text{supp } \mu \subset [0, \infty), \text{ without a singular nonatomic part} \end{array} \right\}$

$u \in L^p(0, \infty) \Rightarrow y \in L^p(0, \infty)$
 $(1 \leq p \leq \infty)$

(3) $A(\mathbb{D}^n)$

Abstract approach

\mathcal{R} = ring of stable transfer functions.

Unstable systems:

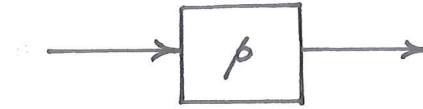
$$p \in \mathbb{F}(\mathcal{R}) = \left\{ \frac{n}{d} : n, d \in \mathcal{R}, d \neq 0 \right\}$$

Example: $g(s) = \frac{1}{s-1} \notin \mathcal{RH}^\infty$

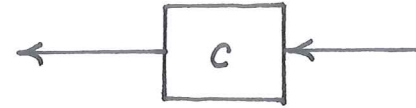
$$= \frac{\frac{1}{s+1}}{\frac{s-1}{s+1}} \in \mathbb{F}(\mathcal{RH}^\infty).$$

Stabilization problem

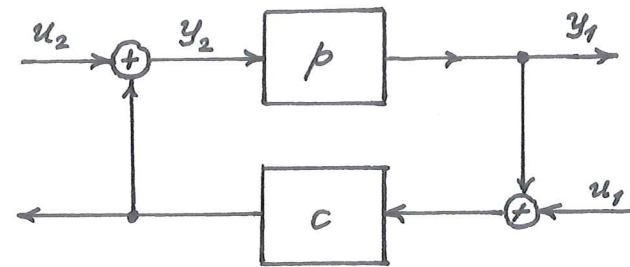
Given a $p \in \mathbb{F}(\mathbb{R})$,



find a $c \in \mathbb{F}(\mathbb{R})$,



such that their interconnection is stable.



That is, $H(p, c) := \begin{bmatrix} p \\ 1 \end{bmatrix} (1 - cp)^{-1} \begin{bmatrix} -c & 1 \end{bmatrix} \in \mathbb{R}^{2 \times 2}$

closed loop transfer function $\left(\begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \mapsto \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} \right)$.

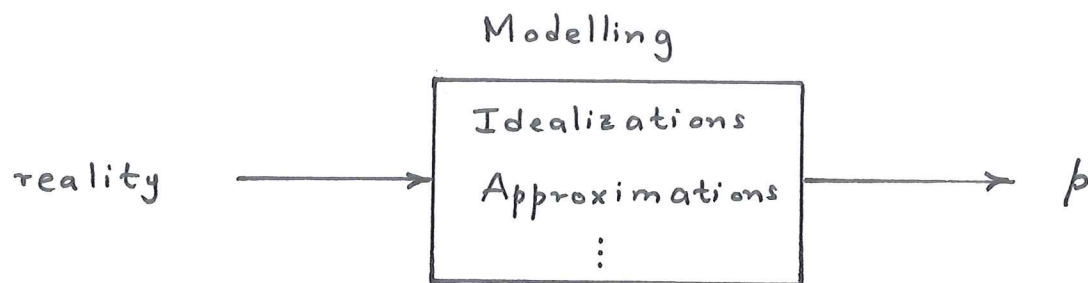
Solution

$p \in \mathbb{F}(R)$ has a coprime factorization if $p = \frac{n}{d}$, $n, d \in R$, $d \neq 0$

and $\exists x, y \in R$ s.t. $nx + dy = 1$.

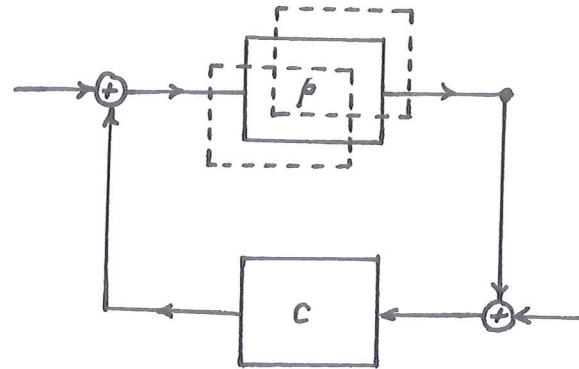
(Then $c := -\frac{x}{y}$ stabilizes p .)

But in reality, p is not known exactly:



Result : p is all wrong!

Robust stabilization



Want c to stabilize not only p , but all \tilde{p} 's "near" p .

What is an appropriate notion of closeness between unstable plants?

Want : d which

- (1) is a metric on $\{\text{stabilizable plants}\}$
- (2) is easy to compute
- (3) has good properties in robust stabilization.

Classical ν -metric d_ν (Glenn Vinnicombe; 1993)

$$\mathbb{R} = \mathbb{R}H^\infty \subset \mathbb{C}(\mathbb{T})$$

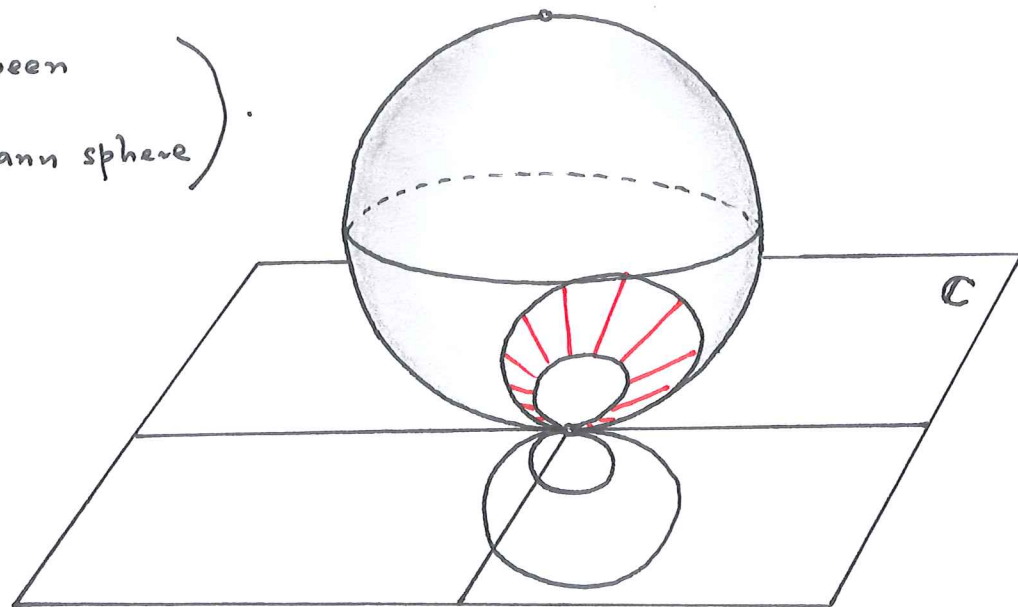
$$X = \{ p \in F(\mathbb{R}H^\infty) : p \text{ has a normalized coprime factorization} \}$$

$$p = \frac{n}{d}; \quad n, d \in \mathbb{R}, d \neq 0; \quad \exists x, y \in \mathbb{R} \text{ s.t. } nx + dy = 1 \text{ and } |n|^2 + |d|^2 = 1 \text{ on } i\mathbb{R}.$$

$$\text{For } p_1, p_2 \in X, \quad d_\nu(p_1, p_2) := \begin{cases} \|n_2 d_1 - n_1 d_2\|_\infty & \text{if } \omega(n_1 \bar{n}_2 + d_1 \bar{d}_2) = 0 \\ 1 & \text{otherwise} \end{cases}$$

If $d_\nu(p_1, p_2) < 1$, then

$$d_\nu(p_1, p_2) = \sup_{y \in \mathbb{R}} \left(\text{chordal distance between } p_1(iy), p_2(iy) \text{ on Riemann sphere} \right).$$



Why winding number constraint?

$p \in \mathbb{R}H^\infty$ stable ; stabilized by $c=0$.

But every neighbourhood of p in the chordal metric has unstable plants.
So stabilizability is not a robust property of the plant.

d_v 's good property w.r.t. robust stabilization.

Stability margin $\mu_{p,c} := \frac{1}{\|H(p,c)\|_\infty}$ large $\mu_{p,c} \Rightarrow$ more stable; better performance

Measures "How stable is the closed loop system?"

Theorem $\mu_{\tilde{p},c} \geq \mu_{p,c} - d_v(p, \tilde{p})$

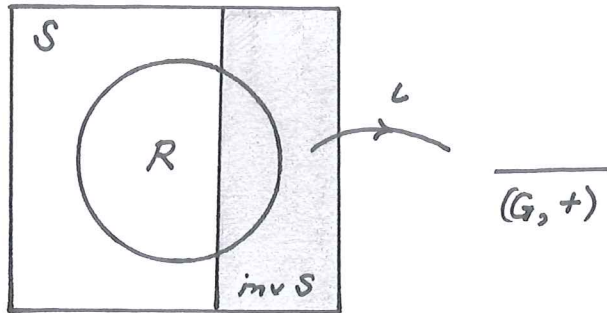
If c stabilizes p and $d_v(p, \tilde{p})$ small enough,
then c also stabilizes \tilde{p} and guarantees a certain performance.

Classical v -metric

What if $R \neq \mathbb{R}H^\infty$? For example, $R = \mathcal{A}^+$?

Extension of the ν -metric

Abstract set-up:



R commutative integral domain with identity

S commutative complex semisimple Banach algebra with an involution \cdot^* and with identity

$\text{inv } S :=$ set of invertible elements of S

$(G, +)$ Abelian group with identity 0

Index function

$L: \text{inv } S \rightarrow (G, +)$ s.t

$$(I1) \quad L(ab) = L(a) + L(b)$$

$$(I2) \quad L(a^*) = -L(a)$$

(I3) L is locally constant (G has discrete topology)

(I4) $x \in R \cap (\text{inv } S)$ invertible in R iff $L(x) = 0$.

What is the extension of d_v ?

$X := \{ p \in \mathbb{F}(R) : p \text{ has a } \underline{\text{normalized coprime factorization}} \}$

$$p = \frac{n}{d} \quad \text{s.t.} \quad (1) \quad n, d \in R, d \neq 0$$

$$(2) \quad \exists x, y \in R \quad \text{s.t.} \quad nx + dy = 1$$

$$(3) \quad n^*n + d^*d = 1 \quad \text{in } S.$$

$$\text{For } p_1, p_2 \in X, \quad d_v(p_1, p_2) := \begin{cases} \|n_2 d_1 - n_1 d_2\|_\infty & \text{if } n_1 n_2^* + d_1 d_2^* \in \text{inv } S \text{ and} \\ & L(n_1 n_2^* + d_1 d_2^*) = 0, \\ 1 & \text{otherwise} \end{cases}$$

$\|\cdot\|_\infty$?

$M(S)$ = maximal ideal space of the Banach algebra S

$x \in S$; $\hat{x} \in C(M(S); \mathbb{C})$ Gelfand transform

$$\hat{x}(\varphi) := \varphi(x) \quad (\varphi \in M(S))$$

$$\|x\|_\infty := \sup_{\varphi \in M(S)} |\hat{x}(\varphi)|.$$

Theorem 1 d_v is a metric on X .

Theorem 2 $\mu_{\tilde{p},c} \geq \mu_{p,c} - d_v(p, \tilde{p})$.

Here $\mu_{p,c} := \frac{1}{\|H(p,c)\|_\infty}$ if p is stabilized by c .

Examples

(1)

$$R = \mathbb{R}H^\infty$$

$$S = C(\mathbb{T})$$

$$G = \mathbb{Z}$$

$$L = \text{winding number } \omega: \text{inv } C(\mathbb{T}) \rightarrow \mathbb{Z}$$

Then $d_\nu = \text{classical } \nu\text{-metric.}$

Also $R = A(\mathbb{D}), W^+(\mathbb{D}), \widehat{L^1(0, \infty)} + \mathbb{C}, \dots$

$$(2) \quad \mathcal{R} = \mathcal{A}^+ = \left\{ \hat{\mu} : \begin{array}{l} \mu \text{ complex Borel measure on } \mathbb{R}, \\ \text{supp } \mu \subset [0, \infty), \text{ without singular nonatomic part} \end{array} \right\}$$

$$= \left\{ \hat{f}_a + \sum_{k \geq 0} f_k e^{-\cdot t_k} : \begin{array}{l} f_a \in L^1(0, \infty) \\ (f_k)_{k \geq 0} \in \ell^1 \\ t_0 = 0 < t_1, t_2, t_3, \dots \end{array} \right\}$$

$$\mathcal{S} = \mathcal{A} = \left\{ \hat{f}_a + \sum_{k \in \mathbb{Z}} f_k e^{-\cdot t_k} : \begin{array}{l} f_a \in L^1(\mathbb{R}) \\ (f_k)_{k \in \mathbb{Z}} \in \ell^1 \end{array} \right\}$$

$$F = \hat{f}_a + \underbrace{\sum_{k \in \mathbb{Z}} f_k e^{-\cdot t_k}}_{F_{AP}} ; \quad \|F\|_{\mathcal{A}} = \|f_a\|_{L^1} + \|(f_k)_{k \in \mathbb{Z}}\|_{\ell^1}$$

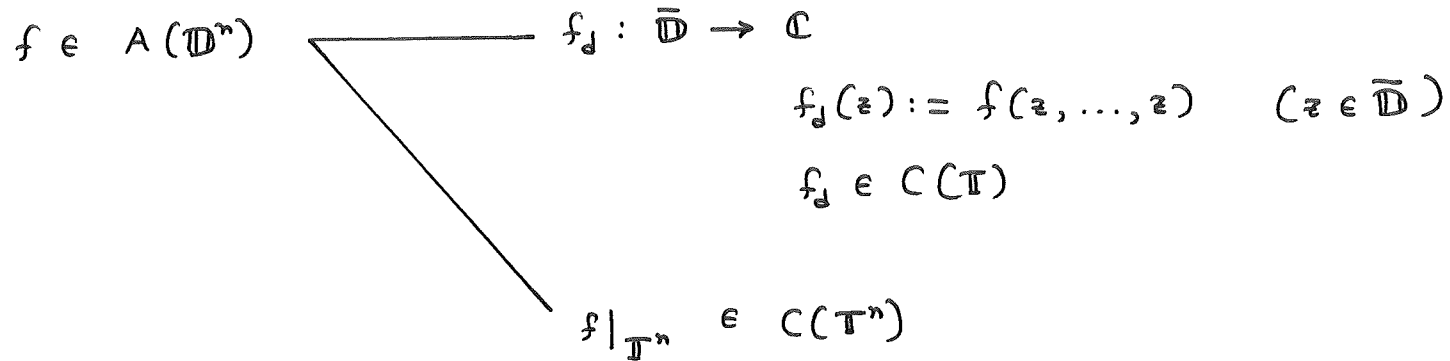
$$G = \mathbb{R} \times \mathbb{Z}$$

$$L(F) = L(\hat{f}_a + F_{AP}) = \left(\omega_{av}(F_{AP}), \omega(1 + F_{AP}^{-1} \hat{f}_a) \right)$$

$$\text{for } F = \hat{f}_a + f_{AP} \in \text{inv } \mathcal{A}.$$

(3) $R = A(\mathbb{D}^n)$ polydisk algebra

$$S = C(\mathbb{T}^n) \times C(\mathbb{T})$$



$$\begin{aligned}
 A(\mathbb{D}^n) &\longrightarrow C(\mathbb{T}^n) \times C(\mathbb{T}) \\
 f &\longmapsto (f|_{\mathbb{T}^n}, f_d)
 \end{aligned}$$

$$G = \mathbb{Z}$$

$$\iota = ((g, h) \mapsto \omega(h))$$

Relation to the gap topology

Theorem

The v -metric topology coincides with the gap metric topology for stabilizable plants over \mathcal{A}^+ .