

Indirect damping for coupled systems

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CDPS 2011

University of Wuppertal

July 18-22, 2011



Outline

Indirect stabilization of weakly coupled systems

Abstract set-up

Systems with standard boundary conditions

Systems with hybrid boundary conditions

Remarks and open problems



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a conservative system

$\Omega \subset \mathbb{R}^n$ bounded the wave equation

$$\begin{aligned} \partial_t^2 v - \Delta v &= 0 && \text{in } \Omega \times \mathbb{R}, \\ v &= 0 && \text{on } \partial\Omega \times \mathbb{R}, \end{aligned}$$

describes a conservative system: the energy of a solution

$$E(u(t)) = \frac{1}{2} \int_{\Omega} \left(|Du(t, x)|^2 + |\partial_t u(t, x)|^2 \right) dx$$

is constant in t



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a dissipative system

the damped wave equation

$$\begin{aligned} \partial_t^2 u - \Delta u + \partial_t u &= 0 && \text{in} && \Omega \times \mathbb{R}, \\ u &= 0 && \text{on} && \partial\Omega \times \mathbb{R}, \end{aligned}$$

is exponentially stable as $t \rightarrow \infty$

$$E(u(t)) \leq E(u(0))e^{c(1-t)} \quad (c > 0)$$



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a weakly coupled system

consider the coupling through zero order terms

$$\begin{cases} \partial_t^2 u - \Delta u + \partial_t u + \alpha v = 0 \\ \partial_t^2 v - \Delta v + \alpha u = 0 \end{cases} \quad \text{in } \Omega \times \mathbb{R}$$

$$u = 0 = v \quad \text{on } \partial\Omega \times \mathbb{R}$$

any kind of stability for $\alpha \neq 0$?



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lack of exponential stability

recast

$$\begin{cases} \partial_t^2 u - \Delta u + \partial_t u + \alpha v = 0 \\ \partial_t^2 v - \Delta v + \alpha u = 0 \end{cases} \quad \text{in } \Omega \times \mathbb{R}$$

as an evolution equation in $\mathcal{H} = [H_0^1(\Omega) \times L^2(\Omega)]^2$

$$\begin{pmatrix} u \\ u' \\ v \\ v' \end{pmatrix}' = \begin{pmatrix} L_1 & K \\ K & L_2 \end{pmatrix} \begin{pmatrix} u \\ u' \\ v \\ v' \end{pmatrix} =: \mathcal{L} \begin{pmatrix} u \\ u' \\ v \\ v' \end{pmatrix},$$

- ▶ L_1, L_2 generators of \mathcal{C}_0 -semigroups on $H_0^1(\Omega) \times L^2(\Omega)$
- ▶ K compact operator in $H_0^1(\Omega) \times L^2(\Omega)$



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lack of exponential stability (ctnd)

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- ▶ $\omega_0(\mathcal{L}) =$ type of the semigroup generated by \mathcal{L}
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(blind to compact perturbations)

$$\omega_0(\mathcal{L}) \geq \omega_{\text{ess}}(\mathcal{L}) = \omega_{\text{ess}} \begin{pmatrix} L_1 & K \\ 0 & L_2 \end{pmatrix} \geq \omega_{\text{ess}}(L_2) = 0.$$

⇒ system cannot be exponentially stable



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a system of second order evolutions equations

in a separable Hilbert space H

$$\begin{cases} u'' + A_1 u + B u' + \alpha v = 0 \\ v'' + A_2 v + \alpha u = 0 \end{cases}$$

(H1) $A_i : D(A_i) \subset H \rightarrow H$ ($i = 1, 2$) are densely defined closed linear operators such that

$$A_i = A_i^*, \quad \langle A_i u, u \rangle \geq \omega_i |u|^2 \quad (\omega_1, \omega_2 > 0)$$

(H2) B is a bounded linear operator on H such that

$$B = B^*, \quad \langle B u, u \rangle \geq \beta |u|^2 \quad (\beta > 0)$$

(H3) $0 < |\alpha| < \sqrt{\omega_1 \omega_2}$



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energies

energies associated to A_1, A_2

$$E_i(u, p) = \frac{1}{2} \left(|A_i^{1/2} u|^2 + |p|^2 \right)$$

total energy of the system $U = (u, p, v, q)$

$$\mathcal{E}(U) := E_1(u, p) + E_2(v, q) + \alpha \langle u, v \rangle$$

assumptions yield

- ▶ $|u|^2 \leq \frac{2}{\omega_i} E_i(u, p)$
- ▶ $\mathcal{E}(U) \geq \nu(\alpha) \left[E_1(u, p) + E_2(v, q) \right]$



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reduction to a first order system

$$\begin{aligned} \mathcal{H} &= D(A_1^{1/2}) \times H \times D(A_2^{1/2}) \times H \\ (U|\hat{U}) &= \langle A_1^{1/2}u, A_1^{1/2}\hat{u} \rangle + \langle p, \hat{p} \rangle \\ &\quad + \langle A_2^{1/2}v, A_2^{1/2}\hat{v} \rangle + \langle q, \hat{q} \rangle + \alpha \langle u, \hat{v} \rangle + \alpha \langle v, \hat{u} \rangle \end{aligned}$$

system takes the equivalent form

$$\begin{cases} U'(t) = \mathcal{A}U(t) \\ U(0) = U_0 := (u^0, u^1, v^0, v^1). \end{cases}$$

with $\mathcal{A} : D(\mathcal{A}) \subset \mathcal{H} \rightarrow \mathcal{H}$ defined by

$$\begin{cases} D(\mathcal{A}) = D(A_1) \times D(A_1^{1/2}) \times D(A_2) \times D(A_2^{1/2}) \\ \mathcal{A}U = (p, -A_1u - Bp - \alpha v, q, -A_2v - \alpha u) \end{cases}$$



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$$\begin{aligned} \mathcal{H} &= D(A_1^{1/2}) \times H \times D(A_2^{1/2}) \times H \\ (U|\hat{U}) &= \langle A_1^{1/2}u, A_1^{1/2}\hat{u} \rangle + \langle p, \hat{p} \rangle \\ &\quad + \langle A_2^{1/2}v, A_2^{1/2}\hat{v} \rangle + \langle q, \hat{q} \rangle + \alpha \langle u, \hat{v} \rangle + \alpha \langle v, \hat{u} \rangle \end{aligned}$$

system takes the equivalent form

$$\begin{cases} U'(t) = \mathcal{A}U(t) \\ U(0) = U_0 := (u^0, u^1, v^0, v^1). \end{cases}$$

with $\mathcal{A} : D(\mathcal{A}) \subset \mathcal{H} \rightarrow \mathcal{H}$ defined by

$$\begin{cases} D(\mathcal{A}) = D(A_1) \times D(A_1^{1/2}) \times D(A_2) \times D(A_2^{1/2}) \\ \mathcal{A}U = (p, -A_1u - Bp - \alpha v, q, -A_2v - \alpha u) \end{cases}$$



a first stability result

Theorem (ACK 2002)

Assume, for some integer $j \geq 2$,

$$|A_1 u| \leq c |A_2^{j/2} u| \quad \forall u \in D(A_2^{j/2}) \quad (\text{ACK})$$

- ▶ $U_0 \in D(\mathcal{A}^{nj})$ (some $n \geq 1$) $\Rightarrow \mathcal{E}(U(t)) \leq \frac{C_n}{t^n} \sum_{k=0}^{nj} \mathcal{E}(U^{(k)}(0))$
- ▶ $\forall U_0 \in \mathcal{H}, \mathcal{E}(U(t)) \rightarrow 0$ as $t \rightarrow \infty$

observe

$$(\text{ACK}) \iff D(A_2^{j/2}) \subset D(A_1) \quad \& \quad |A_1 A_2^{-j/2} u| \leq c |u|$$



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main tools

proof uses

- ▶ energy dissipation

$$\frac{d}{dt} \mathcal{E}(U(t)) = -|B^{1/2} u'(t)|^2 \quad (U_0 \in D(\mathcal{A}))$$

- ▶ multipliers of the form $A_2^{2-j} v$ and $A_2^{1-j} A_1 u$
- ▶ an abstract decay lemma



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abstract decay lemma

- ▶ $A : D(A) \subset H \rightarrow H$ generator of a C_0 -semigroup
- ▶ $L : H \rightarrow [0, +\infty)$ continuous function

$$\int_0^T L(e^{tA}x) dt \leq c \sum_{k=0}^K L(A^k x)$$

$$\Rightarrow \forall n \geq 1, \forall x \in D(A^{nK}), \forall 0 \leq s \leq T$$

$$\int_s^T L(e^{tA}x) \frac{(t-s)^{n-1}}{(n-1)!} dt \leq c^n (1+K)^{n-1} \sum_{k=0}^{nK} L(e^{sA} A^k x)$$

$$\text{▶ } L(e^{tA}x) \leq L(e^{sA}x) \Rightarrow L(e^{tA}x) \leq c^n (1+K)^{n-1} \frac{n!}{t^n} \sum_{k=0}^{nK} L(A^k x)$$



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example 1: Dirichlet boundary conditions

$\Omega \subset \mathbb{R}^n$ bounded $\Gamma = \partial\Omega$

$$\begin{cases} \partial_t^2 u - \Delta u + \partial_t u + \alpha v = 0 \\ \partial_t^2 v - \Delta v + \alpha u = 0 \end{cases} \quad \text{in } \Omega \times (0, +\infty)$$

with boundary conditions

$$u(\cdot, t) = 0 = v(\cdot, t) \quad \text{on } \Gamma \quad \forall t > 0$$

in this example $A_1 = A = A_2$ with

$$D(A) = H^2(\Omega) \cap H_0^1(\Omega), \quad Au = -\Delta u$$

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conclusion: for $0 < |\alpha| < C_\Omega$

$$\begin{aligned} & \int_{\Omega} \left(|\partial_t u|^2 + |\nabla u|^2 + |\partial_t v|^2 + |\nabla v|^2 \right) dx \\ & \leq \frac{C}{t} \left(\|u^0\|_{2,\Omega}^2 + \|u^1\|_{1,\Omega}^2 + \|v^0\|_{2,\Omega}^2 + \|v^1\|_{1,\Omega}^2 \right) \end{aligned}$$



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example 2: hybrid boundary conditions

Let $\alpha \in \mathbb{R}$ and consider the problem

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$$\begin{aligned} \left(\frac{\partial u}{\partial \nu} + u \right) (\cdot, t) &= 0 \text{ on } \Gamma & \forall t > 0 \\ v(\cdot, t) &= 0 \text{ on } \Gamma \end{aligned}$$



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$$D(A_1) = \left\{ u \in H^2(\Omega) : \frac{\partial u}{\partial \nu} + u = 0 \text{ on } \Gamma \right\}, \quad A_1 u = -\Delta u$$

$$D(A_2) = H^2(\Omega) \cap H_0^1(\Omega), \quad A_2 v = -\Delta v$$

Lemma (ACG)

$D(A_2^{k/2})$ is not included in $D(A_1)$ for any $k \geq 2$

Proof.

$$(k=2) \quad v_0 : \begin{cases} (-\Delta)^2 v = 1 \\ v_0 = 0 = \Delta v_0 \end{cases} \text{ on } \Gamma \quad v_1 := -\Delta v_0$$

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Then

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- ▶ since \mathcal{A} generates a \mathcal{C}_0 -semigroup of contractions,

$$D(\mathcal{A}^m) = (\mathcal{H}, D(\mathcal{A}^k))_{\theta,2}$$

if $\theta k = m$ for some $0 < \theta < 1$ and $k, m \in \mathbb{N}$



ACG with data in interpolation spaces

assume

$$D(A_2) \subset D(A_1^{1/2}) \quad \& \quad |A_1^{1/2}u| \leq c|A_2u| \quad (\text{ACG})$$

let $n \geq 1$, $0 < \theta < 1$ then

$$\triangleright U_0 \in (\mathcal{H}, D(\mathcal{A}^{4n}))_{\theta,2} \implies \|U(t)\|_{\mathcal{H}}^2 \leq \frac{C_{n,\theta}}{t^{n\theta}} \|U_0\|_{(\mathcal{H}, D(\mathcal{A}^{4n}))_{\theta,2}}^2$$

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the energy of the solution to the boundary-value problem

$$\begin{cases} \partial_t^2 u - \Delta u + \partial_t u + \alpha v = 0 \\ \partial_t^2 v - \Delta v + \alpha u = 0 \end{cases} \quad \text{in } \Omega \times (0, +\infty)$$

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proof

- ▶ recall

$$D(A_1) = \left\{ u \in H^2(\Omega) : \frac{\partial u}{\partial \nu} + u = 0 \text{ on } \Gamma \right\}, \quad A_1 u = -\Delta u$$

$$D(A_2) = H^2(\Omega) \cap H_0^1(\Omega), \quad A_2 v = -\Delta v$$

- ▶ to obtain, for all $u \in D(A_1), v \in D(A_2)$,

$$|\langle A_1 u, v \rangle| = \left| \int_{\Omega} \nabla u \nabla v \, dx \right| \leq c \langle A_1 u, u \rangle^{1/2} |A_2 v|$$

since $\langle A_1 u, u \rangle = \int_{\Omega} |\nabla u|^2 \, dx + \int_{\Gamma} |u|^2 \, dS$

- ▶ yields (ACG): $D(A_2) \subset D(A_1^{1/2})$ & $|A_1^{1/2} u| \leq c |A_2 u|$



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application

consider boundary-value problem

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different coupling parameters

for general $\alpha_1, \alpha_2 \in \mathbb{R}$ consider

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- ▶ above results can be generalized replacing (H3) with

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- ▶ $\mathcal{E}(U) := \alpha_2 E_1(u, p) + \alpha_1 E_2(v, q) + \alpha_1 \alpha_2 \langle u, v \rangle$

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why not $\alpha_1 = 0$?

- ▶ let $A_1 = A_2 =: A$
with positive eigenvalues $\omega_k \rightarrow +\infty$ and eigenspaces $(Z_k)_{k \geq 1}$
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$$v''(t) + Av(t) + \alpha u(t) = 0 \quad (1)$$

is given by $v(t) = v_1(t) + v_2(t) \in Z_1 + Z_1^\perp$ where

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is given by $v(t) = v_1(t) + v_2(t) \in Z_1 + Z_1^\perp$ where

$$\begin{cases} v_1''(t) + \omega_1 v_1(t) + \alpha u(t) = 0 \\ v_2''(t) + Av_2(t) = 0 \end{cases}$$

thus, the energy

$$E(v_2(t), v_2'(t)) = \frac{1}{2} (|v_2'(t)|^2 + \langle Av_2(t), v_2(t) \rangle) = \text{const}$$

hence, $v^0 \notin Z_1$, $v^1 \notin Z_1$ ensure that the system is not stabilizable



open problems

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- ▶ consider boundary control with hybrid boundary conditions
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Thank you for your attention
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